Colloquium Biometricum 44 2014, 57–68

# REGULAR D-OPTIMAL WEIGHING DESIGNS WITH NEGATIVE CORRELATED ERRORS: CONSTRUCTION

### Bronisław Ceranka, Małgorzata Graczyk

Department of Mathematical and Statistical Methods Poznań University of Life Sciences Wojska Polskiego 28, 60-637 Poznań, Poland e-mails: bronicer@up.poznan.pl, magra@up.poznan.pl

## Summary

The chemical balance weighing designs satisfying the criterion of D-optimality under assumption that the measurements are negative correlated and they have the same variances are considered. We present new method of construction of D-optimal designs based on the set of the incidence matrices of the balanced bipartite weighing designs. Besides, we give an examples of the design matrix

**Keywords and phrases**: balanced bipartite weighing design, chemical balance weighing design, D-optimality

Classification AMS 2010: 62K05, 62K10

#### 1. Introduction

Suppose, we determine unknown measurements of p objects using n weighing operations. The results of this experiment can be described by the model  $\mathbf{y} = \mathbf{X}\mathbf{w} + \mathbf{e}$ , where

(i) **y** is an  $n \times 1$  random vector of the observations,

- (ii)  $\mathbf{w} = (w_1, w_2, ..., w_p)'$  is a vector representing unknown measurements of objects,
- (iii)  $\mathbf{X} \in \mathbf{\Phi}_{n \times p, m} \{-1, 0, 1\}$ , where  $\mathbf{\Phi}_{n \times p, m} \{-1, 0, 1\}$  denotes the class of  $n \times p$  matrices having entries  $x_{ii} = -1, 1$  or 0,
- (iv) m is the maximum number of elements equal to 1 and -1 in each column of the matrix **X**,
- (v) **e** is the  $n \times 1$  random vector of errors. We shall make two standing assumptions on the maps of our considerations:  $E(\mathbf{e}) = \mathbf{0}_n$  and  $Var(\mathbf{e}) = \sigma^2 \mathbf{G}$ , where

$$\mathbf{G} = g((1-\rho)\mathbf{I}_{n} + \rho \mathbf{1}_{n}\mathbf{1}_{n}), \ g > 0, \ \frac{-1}{n-1} < \rho < 0.$$
(1.1)

In the case where  $\rho \in \left(\frac{-1}{n-1}, 0\right)$  and  $g > 0, \mathbf{G}$  is positive definite. So, if the matrix  $\mathbf{X}$  is of full column rank, then using the weighted lest squares method we obtain the best linear unbiased estimator  $\hat{\mathbf{w}} = (\mathbf{X}'\mathbf{G}^{-1}\mathbf{X})^{-1}\mathbf{X}'\mathbf{G}^{-1}\mathbf{y}$ with the variance matrix  $\operatorname{Var}(\hat{\mathbf{w}}) = \sigma^2 (\mathbf{X}'\mathbf{G}^{-1}\mathbf{X})^{-1}$ . The matrix  $\mathbf{M} = \mathbf{X}'\mathbf{G}^{-1}\mathbf{X}$  is called the information matrix of the design  $\mathbf{X}$ .

The optimality problem is concerned with efficient estimation in some sense by a proper choice of the design matrix  $\mathbf{X}$ . There are many possible optimality criteria. One of them is D-optimality. This optimality criterion minimizes the determinant of the matrix  $\mathbf{M}^{-1}$ . The design  $\mathbf{X}_D$  is called D-optimal in the class of all possible design matrices  $\mathbf{\Phi}_{n \times p,m} \{-1, 0, 1\}$  if  $\det(\mathbf{X}_D) = \min(\det(\mathbf{M}^{-1}): \mathbf{X} \in \mathbf{\Phi}_{n \times p,m} \{-1, 0, 1\})$ . If  $\det(\mathbf{X}_D)$  attains the lowest bound then the design is called regular D-optimal. In other cases it is called D-optimal. The research related to D-optimality was presented for instance in Raghavarao (1971), Shah and Sinha (1989). Some results concerned on the regular D-optimal chemical balance weighing designs are given in literature including Gail and Kiefer (1982), Jacroux et al. (1983), Chadjiconstantinidis and Chadjipadelis (1994), Koukouvinos (1996), Abrego et al. (2003), Masaro and Wong (2008) ones.

Ceranka and Graczyk (2014a) gave the definition of the regular D-optimal chemical balance weighing design and the conditions determining regular D-optimal design for  $\rho \in \left(\frac{-1}{n-1}, 0\right)$ .

**Definition 1.1.** Let  $\rho \in \left(\frac{-1}{n-1}, 0\right)$ . Any chemical balance weighing design

 $\mathbf{X} \in \mathbf{\Phi}_{n \times p,m} \{-1, 0, 1\}$  with the covariance matrix of errors  $\sigma^2 \mathbf{G}$ , where  $\mathbf{G}$  is given by (1.1), is regular D-optimal if

$$\det(\mathbf{M}^{-1}) = \left(g(1-\rho)\left(m - \frac{\rho(m-2u)^2}{1+\rho(n-1)}\right)^{-1}\right)^p, \text{ where } u = \min\{u_1, u_2, \dots, u_p\}, u_j$$

represent the number of elements equal to -1 in j th column of **X**, j = 1, 2, ..., p.

**Theorem 1.1**. Any chemical balance weighing design  $\mathbf{X} \in \mathbf{\Phi}_{n \times p,m} \{-1, 0, 1\}$  with the covariance matrix of errors  $\sigma^2 \mathbf{G}$ , where  $\mathbf{G}$  is given by (1.1), is regular D-optimal if and only if

$$\mathbf{X}'\mathbf{X} = m\mathbf{I}_p - \frac{\rho(m-2u)^2}{1+\rho(n-1)} \left(\mathbf{I}_p + \mathbf{1}_p \mathbf{1}_p'\right)$$
(1.2)

$$\mathbf{X}\mathbf{\hat{1}}_{n} = \mathbf{z}_{p}, \qquad (1.3)$$

where  $\mathbf{z}_p$  is  $p \times 1$  vector for which the *j* th element is equal to -(m-2u) or m-2u, j=1,2,...,p.

### 2. The construction

For  $\mathbf{X} \in \mathbf{\Pi}_{n \times p} \{-1, 1\}$ , where  $\mathbf{\Pi}_{n \times p} \{-1, 1\}$  denotes the class of  $n \times p$  matrices having entries  $x_{ij} = -1$  or 1, some constructions of regular D-optimal designs were given in Masaro and Wong (2008). In more extensive class of the

design matrices  $\mathbf{\Phi}_{n \times p,m}$ {-1, 0, 1}, the problem of optimality in weighing designs was considered in Ceranka and Graczyk (2014a).

In this Section we present new method of construction of the regular D-optimal chemical balance weighing design based on the set of the incidence matrices of balanced bipartite weighing designs. This construction was motivated by the properties of such designs. For a deeper discussion of such designs we refer the reader to Huang (1976). Let  $\mathbf{N}_{h}^{*}$  (h = 1, 2, ..., t), be the incidence matrix of balanced bipartite weighing design with the parameters v,  $b_{h}$ ,  $r_{h}$ ,  $k_{1h}$ ,  $k_{2h}$ ,  $\lambda_{1h}$ ,  $\lambda_{2h}$ . From  $\mathbf{N}_{h}^{*}$  we form the matrix  $\mathbf{N}_{h}$  by replacing  $k_{1h}$  unities equal to +1 of each column which correspond to the elements belonging to the first subblock by -1. Then each column of the matrix  $\mathbf{N}_{h}$  will contain  $k_{1h}$  elements equal to -1,  $k_{2h}$  elements equal to 1 and  $v - k_{1h} - k_{2h}$  elements equal to 0. Let  $\mathbf{X} \in \mathbf{\Phi}_{n \times p, m} \{-1, 0, 1\}$  be the design matrix of the chemical balance weighing design in the form

$$\mathbf{X} = \begin{bmatrix} \mathbf{N}_1 & \mathbf{N}_2 & \cdots & \mathbf{N}_t \end{bmatrix}^{\mathsf{T}}.$$
 (2.1)

Therefore in such design we determine unknown measurements of p = vobjects in  $n = \sum_{h=1}^{t} b_h$  measurement operations, each object is weighted  $m = \sum_{h=1}^{t} r_h$  times.

The result given by Ceranka and Graczyk (2014b) will be needed for next considerations.

**Lemma 2.1.** The chemical balance weighing design with the design matrix  $\mathbf{X} \in \mathbf{\Phi}_{n \times p, m} \{-1, 0, 1\}$  given by (2.1) is nonsingular if and only if

$$k_{1h} \neq k_{2h} \tag{2.2}$$

for at least one h = 1, 2, ..., t.

Without loss of generality, we can assume that  $k_{1h} \neq k_{2h}$  for each h. Then  $r_{1h} = \frac{\lambda_{1h}(v-1)}{2k_{2h}}$  and  $r_{2h} = \frac{\lambda_{1h}(v-1)}{2k_{1h}}$ , h = 1, 2, ..., t, are the numbers of elements equal to -1 and 1 in each column of  $\mathbf{N}_{h}$ . We will work under this assumption.

Ceranka and Graczyk (2014a) gave the condition determining regular D-optimal design for the case  $\rho \in \left(\frac{-1}{n-1}, 0\right)$ .

From Theorem 1.1 we can see that the optimality conditions are depended on the parameter  $\rho$  in (1.1). This implies that the methods of construction of the design  $\mathbf{X} \in \mathbf{\Phi}_{n \times p,m} \{-1, 0, 1\}$  are depended on  $\rho$ , either. Therefore we will formulate our main result that provides criteria of the regular D-optimal designs.

**Theorem 2.1.** Let  $k_{1h} \neq k_{2h}$  for each h = 1, 2, ..., t. Any chemical balance weighing design  $\mathbf{X} \in \mathbf{\Phi}_{n \times p, m} \{-1, 0, 1\}$  in the form (2.1) with the covariance matrix of errors  $\sigma^2 \mathbf{G}$ , where  $\mathbf{G}$  is given by (1.1), is regular D-optimal if and only if the following conditions are simultaneously satisfied

$$\rho = \frac{\sum_{h=1}^{t} (\lambda_{2h} - \lambda_{1h})}{\left(\sum_{h=1}^{t} (r_{2h} - r_{1h})\right)^2 - \left(\sum_{h=1}^{t} b_h - 1\right) \left(\sum_{h=1}^{t} (\lambda_{2h} - \lambda_{1h})\right)}, \qquad (2.3)$$

$$\sum_{h=1}^{t} (\lambda_{2h} - \lambda_{1h}) < 0, \qquad (2.4)$$

$$\left(\sum_{h=1}^{t} (r_{2h} - r_{1h})\right)^2 \neq 0.$$
(2.5)

**Proof.** From Theorem 1.1 it follows that if  $\rho \in \left(\frac{-1}{n-1}, 0\right)$  then chemical balance weighing design is regular D-optimal if the conditions (1.2) and (1.3) hold. From  $\mathbf{X}' \mathbf{1}_n = \mathbf{z}_p$  we have  $\mathbf{c}_j \mathbf{X}' \mathbf{1}_n = m - 2u$  or -(m - 2u), j = 1, 2, ..., p, where  $m - 2u = \sum_{h=1}^{t} (r_{2h} - r_{1h})$ ,  $\mathbf{c}_j$  is the *j* th column of matrix  $\mathbf{I}_p$ . From the condition  $\mathbf{X}' \mathbf{X} = m \mathbf{I}_p - \frac{\rho(m - 2u)^2}{1 + \rho(n-1)} (\mathbf{I}_p - \mathbf{1}_p \mathbf{1}_p)$  we obtain  $\mathbf{c}_j \mathbf{X}' \mathbf{X} \mathbf{c}_j = \frac{\rho(m - 2u)^2}{1 + \rho(n-1)}$  and

h=1

consequently from (1.3) we get  $\mathbf{c}_{j}\mathbf{X}^{T}\mathbf{X}\mathbf{c}_{j} = \sum_{h=1}^{t} (\lambda_{2h} - \lambda_{1h})$ . Then

$$\sum_{h=1}^{t} (\lambda_{2h} - \lambda_{1h}) = \frac{\rho \left( \sum_{h=1}^{t} (r_{2h} - r_{1h}) \right)^{-1}}{1 + \rho \left( \sum_{h=1}^{t} b_{h} - 1 \right)^{-1}}$$
 and thus we have (2.3). Moreover, under the

condition (2.4), the denominator of (2.3) is greater than zero, hence  $\rho < 0$ . Since (2.5) then  $\rho \in \left(\frac{-1}{n-1}, 0\right)$ . If (2.5) is not fulfilled then  $\rho = -(n-1)^{-1}$  and in that case the matrix **G** is not positive definite. This completes the proof.

**Theorem 2.2.** Let t = 1. If for a given  $\rho$ , the parameters of the balanced bipartite weighing design are equal to

- (i)  $\rho = -2(108s^2 24s 1)^{-1}$ , v = 6s,  $b_1 = 6s(6s 1)$ ,  $r_1 = 3(6s 1)$ ,  $k_1 = 1, k_2 = 2, \lambda_1 = 4, \lambda_2 = 2, s = 1, 2, ...,$
- (ii)  $\rho = -(4s^2 + s 1)^{-1}$ , v = 2s + 1,  $b_1 = s(2s + 1)$ ,  $r_1 = 8s$ ,  $k_1 = 3$ ,  $k_2 = 5$ ,  $\lambda_1 = 15$ ,  $\lambda_2 = 13$ , s = 4,5,...,
- (iii)  $\rho = -(3s^2 + s 1)^{-1}$ , v = 2s + 1,  $b_1 = s(2s + 1)$ ,  $r_1 = 3s$ ,  $k_1 = 1$ ,  $k_2 = 2$ ,  $\lambda_1 = 2$ ,  $\lambda_2 = 1$ , s = 2,3,..., except the case s = 5,
- (iv)  $\rho = -(5s^2 + s 1)^{-1}, v = 4s + 1, b_1 = s(4s + 1), r_1 = 5s, k_1 = 2, k_2 = 3,$  $\lambda_1 = 3, \lambda_2 = 2, s = 2,3,...,$
- (v)  $\rho = -(6s^2 + s 1)^{-1}, v = 2s + 1, b_1 = s(2s + 1), r_1 = 6s, k_1 = 2, k_2 = 4,$  $\lambda_1 = 8, \lambda_2 = 7, s = 3, 4, \dots,$
- (vi)  $\rho = -(6s^2 5s)^{-1}$ , v = 2s,  $b_1 = s(2s 1)$ ,  $r_1 = 3(2s 1)$ ,  $k_1 = 2$ ,  $k_2 = 4$ ,  $\lambda_1 = 8$ ,  $\lambda_2 = 7$ ,  $s = 3, 4, \dots$ ,

then the chemical balance weighing design  $\mathbf{X} \in \mathbf{\Phi}_{n \times p,m} \{-1, 0, 1\}$  in the form (2.1) with the covariance matrix of errors  $\sigma^2 \mathbf{G}$ , where  $\mathbf{G}$  is given by (1.1), is regular D-optimal.

**Proof**. The proof is immediate by observing that the parameters given in (i)-(vi) satisfy the conditions (2.3)-(2.5).

**Theorem 2.3.** Let t = 2. If for a given  $\rho$ , the parameters of the balanced bipartite weighing design are equal to

(i)  $\rho = -3(306s^2 - 21s + 1)^{-1}$ , v = 6s,  $b_1 = 6s(6s - 1)$ ,  $r_1 = 3(6s - 1)$ ,  $k_{11} = 1$ ,  $k_{21} = 2$ ,  $\lambda_{11} = 4$ ,  $\lambda_{21} = 2$ , and v = 6s,  $b_2 = 3s(6s - 1)$ ,  $r_2 = 3(6s - 1)$ ,  $k_{12} = 2$ ,  $k_{22} = 4$ ,  $\lambda_{12} = 8$ ,  $\lambda_{22} = 7$ , s = 1, 2, ...,

(ii) 
$$\rho = -2((2t+1)^2(6s-1)^2 + 2(6s(6s-1)(t+1)-1))^{-1}, v = 6s,$$
  
 $b_1 = 6s(6s-1), r_1 = 3(6s-1), k_{11} = 1, k_{21} = 2, \lambda_{11} = 4, \lambda_{21} = 2$  and  
 $v = 6s, b_2 = 6ts(6s-1), r_2 = 4t(6s-1), k_{12} = 1, k_{22} = 3, \lambda_{12} = 6t,$   
 $\lambda_{22} = 6t, s, t = 1, 2, ...,$ 

(iii) 
$$\rho = -2((t+1)^2(6s-1)^2 + 2(2s(6s-1)(t+3)-1))^{-1}$$
,  $v = 6s$ ,  
 $b_1 = 6s(6s-1)$ ,  $r_1 = 3(6s-1)$ ,  $k_{11} = 1$ ,  $k_{21} = 2$ ,  $\lambda_{11} = 4$ ,  $\lambda_{21} = 2$  and  
 $v = 6s$ ,  $b_2 = 2ts(6s-1)$ ,  $r_2 = 3t(6s-1)$ ,  $k_{12} = 3$ ,  $k_{22} = 6$ ,  $\lambda_{12} = 12t$ ,  
 $\lambda_{22} = 12t$ ,  $s, t = 1, 2, ...,$ 

(iv) 
$$\rho = -(7s^2 + 2s - 1)^{-1}$$
,  $v = 2s + 1$ ,  $b_1 = s(2s + 1)$ ,  $r_1 = 8s$ ,  $k_{11} = 3$ ,  
 $k_{21} = 5$ ,  $\lambda_{11} = 15$ ,  $\lambda_{21} = 13$  and  $v = 2s + 1$ ,  $b_2 = s(2s + 1)$ ,  $r_2 = 3s$ ,  
 $k_{12} = 1$ ,  $k_{22} = 2$ ,  $\lambda_{12} = 2$ ,  $\lambda_{22} = 1$ ,  $s = 6,7,...$ ,

- (v)  $\rho = -3(61s^2 + 9s 3)^{-1}$ , v = 4s + 1,  $b_1 = 2s(4s + 1)$ ,  $r_1 = 16s$ ,  $k_{11} = 3$ ,  $k_{21} = 5$ ,  $\lambda_{11} = 15$ ,  $\lambda_{21} = 13$  and v = 4s + 1,  $b_2 = s(4s + 1)$ ,  $r_2 = 5s$ ,  $k_{12} = 2$ ,  $k_{22} = 3$ ,  $\lambda_{12} = 3$ ,  $\lambda_{22} = 2$ , s = 2,3,...,
- (vi)  $\rho = -3(28s^2 + 6s 3)^{-1}$ , v = 2s + 1,  $b_1 = s(2s + 1)$ ,  $r_1 = 8s$ ,  $k_{11} = 3$ ,  $k_{21} = 5$ ,  $\lambda_{11} = 15$ ,  $\lambda_{21} = 13$  and v = 2s + 1,  $b_2 = s(2s + 1)$ ,  $r_2 = 6s$ ,  $k_{12} = 2$ ,  $k_{22} = 4$ ,  $\lambda_{12} = 8$ ,  $\lambda_{22} = 7$ , s = 4,5,...,
- (vii)  $\rho = -(61s^2 + 3s 3)^{-1}$ , v = 4s + 1,  $b_1 = 2s(4s + 1)$ ,  $r_1 = 16s$ ,  $k_{11} = 3$ ,  $k_{21} = 5$ ,  $\lambda_{11} = 15$ ,  $\lambda_{21} = 13$  and v = 4s + 1,  $b_2 = s(4s + 1)$ ,  $r_2 = 5s$ ,  $k_{12} = 1$ ,  $k_{22} = 4$ ,  $\lambda_{12} = 2$ ,  $\lambda_{22} = 3$ , s = 2,3,...,

(viii) 
$$\rho = -(256s^2 + 6s - 1)^{-1}$$
,  $v = 10s + 1$ ,  $b_1 = 5s(10s + 1)$ ,  $r_1 = 40s$ ,  
 $k_{11} = 3$ ,  $k_{21} = 5$ ,  $\lambda_{11} = 15$ ,  $\lambda_{21} = 13$  and  $v = 10s + 1$ ,  $b_2 = s(10s + 1)$ ,  
 $r_2 = 6s$ ,  $k_{12} = 1$ ,  $k_{22} = 5$ ,  $\lambda_{12} = 1$ ,  $\lambda_{22} = 2$ ,  $s = 1, 2, ...,$ 

- (ix)  $\rho = -(29s^2 + 2s 1)^{-1}$ , v = 2s + 1,  $b_1 = s(2s + 1)$ ,  $r_1 = 8s$ ,  $k_{11} = 3$ ,  $k_{21} = 5$ ,  $\lambda_{11} = 15$ ,  $\lambda_{21} = 13$  and v = 2s + 1,  $b_2 = s(2s + 1)$ ,  $r_2 = 7s$ ,  $k_{12} = 2$ ,  $k_{22} = 5$ ,  $\lambda_{12} = 10$ ,  $\lambda_{22} = 11$ , s = 4,5,...,
- (x)  $\rho = -(2s^2(t+1)^2 + 2s^2(t+1) + s(t+1) 1)^{-1}, v = 2s+1,$   $b_1 = s(2s+1), r_1 = 8s, k_{11} = 3, k_{21} = 5, \lambda_{11} = 15, \lambda_{21} = 13 \text{ and}$   $v = 2s+1, b_2 = ts(2s+1), r_2 = 4ts, k_{12} = 1, k_{22} = 3, \lambda_{12} = 3t,$  $\lambda_{22} = 3t, s = 4,5,..., t = 1,2,...,$

(xi) 
$$\rho = -2(s^2(3t+2)^2 + 2(s(t+1)(2s+1)-1))^{-1}, v = 2s+1,$$
  
 $b_1 = s(2s+1), r_1 = 8s, k_{11} = 3, k_{21} = 5, \lambda_{11} = 15, \lambda_{21} = 13 \text{ and}$   
 $v = 2s+1, b_2 = ts(2s+1), r_2 = 9ts, k_{12} = 3, k_{22} = 6, \lambda_{12} = 18t,$   
 $\lambda_{22} = 18t, s = 4,5,..., t = 1,2,...,$ 

(xii) 
$$\rho = -(s^2(2t+1)^2 + s(2s+1)(t+1) - 1)^{-1}, \quad v = 2s+1, \quad b_1 = s(2s+1),$$
  
 $r_1 = 3s, \quad k_{11} = 1, \quad k_{21} = 2, \quad \lambda_{11} = 2, \quad \lambda_{21} = 1 \quad \text{and} \quad v = 2s+1,$   
 $b_2 = ts(2s+1), \quad r_2 = 4ts, \quad k_{12} = 1, \quad k_{22} = 3, \quad \lambda_{12} = 3t, \quad \lambda_{22} = 3t,$   
 $s = 2,3,..., t = 1,2,..., \text{ except the case } s = 5,$ 

(xiii) 
$$\rho = -(s^2(3t+1)^2 + s(2s+1)(t+1) - 1)^{-1}$$
,  $v = 2s+1$ ,  $b_1 = s(2s+1)$ ,  
 $r_1 = 3s$ ,  $k_{11} = 1$ ,  $k_{21} = 2$ ,  $\lambda_{11} = 2$ ,  $\lambda_{21} = 1$  and  $v = 2s+1$ ,  
 $b_2 = ts(2s+1)$ ,  $r_2 = 9ts$ ,  $k_{12} = 3$ ,  $k_{22} = 6$ ,  $\lambda_{12} = 18t$ ,  $\lambda_{22} = 18t$ ,  
 $s = 2,3,..., t = 1,2,...$ , except the case  $s = 5$ ,

(xiv) 
$$\rho = -(s^2(4t+1)^2 + s(4s+1)(2t+1) - 1)^{-1}$$
,  $v = 4s+1$ ,  $b_1 = s(4s+1)$ ,  
 $r_1 = 5s$ ,  $k_{11} = 2$ ,  $k_{21} = 3$ ,  $\lambda_{11} = 3$ ,  $\lambda_{21} = 2$  and  $v = 4s+1$ ,  
 $b_2 = 2ts(4s+1)$ ,  $r_2 = 8ts$ ,  $k_{12} = 1$ ,  $k_{22} = 3$ ,  $\lambda_{12} = 3t$ ,  $\lambda_{22} = 3t$ ,  
 $s = 2,3,..., t = 1,2,...,$ 

(xv) 
$$\rho = -(s^2(3t+1)^2 + s(4s+1)(t+1) - 1)^{-1}$$
,  $v = 4s+1$ ,  $b_1 = s(4s+1)$ ,  
 $r_1 = 5s$ ,  $k_{11} = 2$ ,  $k_{21} = 3$ ,  $\lambda_{11} = 3$ ,  $\lambda_{21} = 2$  and  $v = 4s+1$ ,  
 $b_2 = ts(4s+1)$ ,  $r_2 = 9ts$ ,  $k_{12} = 3$ ,  $k_{22} = 6$ ,  $\lambda_{12} = 9t$ ,  $\lambda_{22} = 9t$ ,  
 $s = 2,3,..., t = 1,2,...,$ 

(xvi) 
$$\rho = -(4s^2(3t+1)^2 + s(2s+1)(t+1) - 1)^{-1}$$
,  $v = 2s+1$ ,  $b_1 = s(2s+1)$ ,  
 $r_1 = 6s$ ,  $k_{11} = 2$ ,  $k_{21} = 4$ ,  $\lambda_{11} = 8$ ,  $\lambda_{21} = 7$  and  $v = 2s+1$ ,  
 $b_2 = ts(2s+1)$ ,  $r_2 = 4ts$ ,  $k_{12} = 1$ ,  $k_{22} = 3$ ,  $\lambda_{12} = 3t$ ,  $\lambda_{22} = 3t$ ,  
 $s = 3, 4, \dots, t = 1, 2, \dots$ ,

(xvii) 
$$\rho = -(s^2(3t+2)^2 + s(2s+1)(t+1) - 1)^{-1}$$
,  $v = 2s+1$ ,  $b_1 = s(2s+1)$ ,  
 $r_1 = 6s$ ,  $k_{11} = 2$ ,  $k_{21} = 4$ ,  $\lambda_{11} = 8$ ,  $\lambda_{21} = 7$  and  $v = 2s+1$ ,  
 $b_2 = ts(2s+1)$ ,  $r_2 = 9ts$ ,  $k_{12} = 3$ ,  $k_{22} = 6$ ,  $\lambda_{12} = 18t$ ,  $\lambda_{22} = 18t$ ,  
 $s = 3,4,..., t = 1,2,...,$ 

(xviii) 
$$\rho = -((2s-1)^2(2t+1)^2 + s(2s-1)(2t+1) - 1)^{-1}, v = 2s$$
,  
 $b_1 = s(2s-1), r_1 = 3s(2s-1), k_{11} = 2, k_{21} = 4, \lambda_{11} = 8$ ,  
 $\lambda_{21} = 7$  and  $v = 2s$ ,  $b_2 = 2ts(2s-1), r_2 = 4t(2s-1), k_{12} = 1$ ,  
 $k_{22} = 3, \lambda_{12} = 6t, \lambda_{22} = 6t, s = 3,4,..., t = 1,2,...,$ 

then the chemical balance weighing design  $\mathbf{X} \in \mathbf{\Phi}_{n \times p, m} \{-1, 0, 1\}$  in the form (2.1) with the covariance matrix of errors  $\sigma^2 \mathbf{G}$ , where  $\mathbf{G}$  is given by (1.1), is regular D-optimal.

**Proof.** One can easily check that the parameters given in (i)-(xviii) fulfilled the conditions given in Theorem 2.1. ■

## 3. Examples

Let us consider the experiment where unknown measurements of p = v = 5objects in n = 10 measurement operations are estimated. We assume that each object can be measured m = 6 times. Suppose that the errors of measurements are negative correlated and have the same variances, so  $\mathbf{G} = g\left(\frac{14}{13}\mathbf{I}_n - \frac{1}{13}\mathbf{1}_n\mathbf{1}_n'\right)$ . In this way we determine the regular D-optimal design in the class  $\Phi_{10\times 5,6}\{-1,0,1\}$ . The design  $\mathbf{X} \in \Phi_{10\times 5,6}\{-1,0,1\}$  in the form (2.1) can be constructed from the incidence matrix of balanced bipartite weighing designs with the parameters v = 5, b = 10, r = 6,  $k_1 = 1$ ,  $k_2 = 2$ ,  $\lambda_1 = 2$ ,  $\lambda_2 = 1$  (see, Theorem 2.3 (iii)) and

$$\mathbf{N}^{*} = \begin{bmatrix} 1_{2} & 1_{2} & 1_{2} & 1_{2} & 0 & 1_{1} & 0 & 0 & 1_{1} & 0 \\ 1_{2} & 0 & 0 & 1_{1} & 1_{2} & 1_{2} & 1_{2} & 1_{1} & 0 & 0 \\ 1_{1} & 1_{2} & 0 & 0 & 1_{2} & 0 & 0 & 1_{2} & 1_{2} & 1_{1} \\ 0 & 1_{1} & 1_{2} & 0 & 0 & 1_{2} & 1_{1} & 1_{2} & 0 & 1_{2} \\ 0 & 0 & 1_{1} & 1_{2} & 1_{1} & 0 & 1_{2} & 0 & 1_{2} & 1_{2} \end{bmatrix},$$

where  $l_1$  and  $l_2$  denote that the object exists in the first or in the second subblock, respectively, 0 if the object does not exist in the block. In each incidence matrix of balanced bipartite weighing design we replace the elements that are equal to 1 and correspond to elements belonging to the first subblock  $(l_1)$  by -1. As the next step we built design  $\Phi_{10\times 5,6}\{-1,0,1\}$  in the form (2.1) for t = 1

$$\mathbf{X}' = \begin{vmatrix} 1 & 1 & 1 & 1 & 0 & -1 & 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & -1 & 1 & 1 & 1 & -1 & 0 & 0 \\ -1 & 1 & 0 & 0 & 1 & 0 & 0 & 1 & 1 & -1 \\ 0 & -1 & 1 & 0 & 0 & 1 & -1 & 1 & 0 & 1 \\ 0 & 0 & -1 & 1 & -1 & 0 & 1 & 0 & 1 & 1 \end{vmatrix}$$

and det $(\mathbf{X}'\mathbf{G}^{-1}\mathbf{X})^{-1} = \left(\frac{2g}{13}\right)^5$ .

#### References

- Abrego B., Fernandez-Merchant S., Neubauer G.N., Watkins W. (2003). D-optimal weighing designs for  $n \equiv -1 \mod 4$  objects and a large number of weighings. *Linear Algebra and its Applications* 374, 175–218.
- Ceranka B., Graczyk M. (2014a). The problem of D-optimality in some experimental designs. International Journal of Mathematics and Computer Application Research 4, 11–18.
- Ceranka B., Graczyk M. (2014b). Construction of regular D-optimal weighing designs with nonnegative correlated errors. *Colloquium Biometricum* 44, 43 –56.
- Chadjiconstantinidis S., Chadjipadelis T. (1994). A construction method of new D-A-optimal designs when  $N \equiv 3 \mod 4$  and  $k \le N 1$ . Discrete Mathematics 131, 39–50.
- Gail Z., Kiefer J. (1982). Construction methods for D-optimum weighing designs when  $n \equiv 3 \mod 4$ . Annals of Statistics 10, 502–510.
- Huang C. (1976). Balanced bipartite weighing designs. *Journal of Combinatorial Theory (A)* 21, 20–34.
- Jacroux, M., Wong C.S., Masaro J.C. (1983). On the optimality of chemical balance weighing designs. J. Statist. Plann. Inference 8, 231–240.
- Koukouvinos Ch. (1996). Linear models and D-optimal designs for  $n \equiv 2 \mod 4$ . Statistics and Probability Letters 26, 329–332.
- Masaro J., Wong Ch.S. (2008). D-optimal designs for correlated random vectors. *Journal* of Statistical Planning and Inference 138, 4093–4106.
- Raghavarao D. (1971). Constructions and Combinatorial Problems in designs of Experiments. John Wiley Inc., New York.
- Shah K.R., Sinha B.K. (1989). Theory of optimal designs. Springer-Verlag, Berlin, Heidelberg.